

CAN-2053D Quick Start

Packing List

CAN-2053D



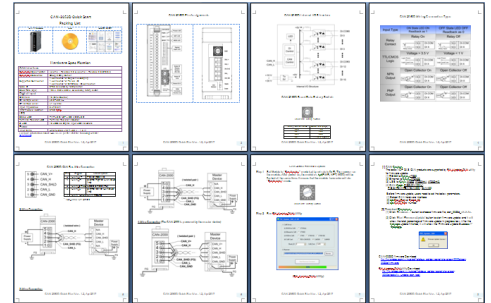
CD



Screw Driver



Quick Start



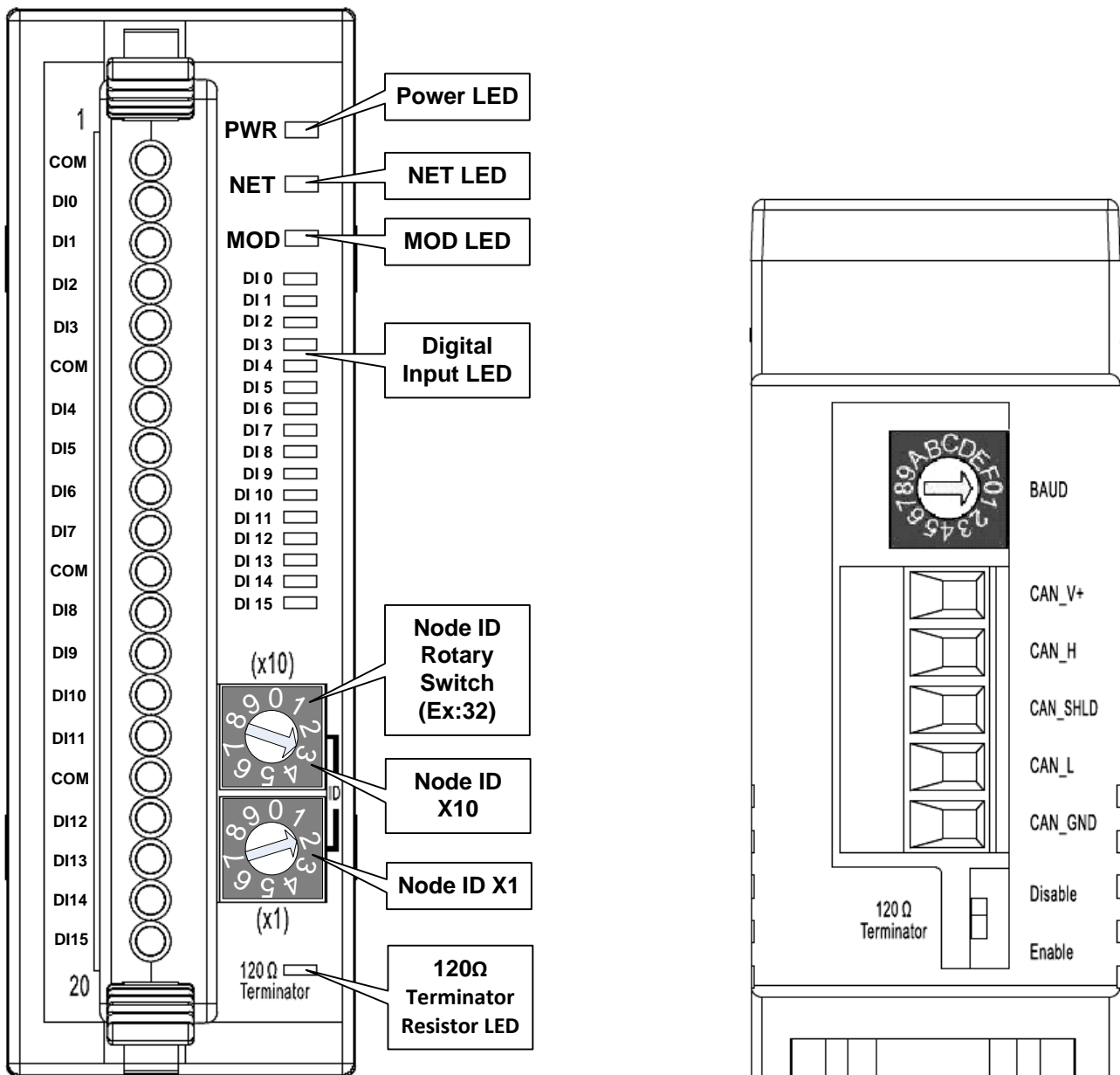
Hardware Specification

CAN Interface	
DeviceNet Specification	Volume I, Release 2.0 & Volume II, Release 2.0, Errata 5
DeviceNet Subscribe	Group 2 Only Server
Supported Connection	1 connection for Explicit Messaging 1 connection for Polled I/O 1 connection for Bit-Strobe I/O connection
Node ID	0~63 selected by rotary switch
Baud Rate (bps)	125 k, 250 k, 500 k, selected by rotary switch
Digital Input	
Channels	16 (Sink/Source)
On Voltage Level	+3.5~+30 V _{DC}
Off Voltage Level	+1 V _{DC} Max.
Input Impedance	3 k Ω , 0.3W
Intra-module Isolation	3750 V _{rms}
LED	
Status LED	PWR LED, NET LED, MOD LED
Terminal Resister LED	Terminal Resister Indicator
DI LED	16 LEDs as Digital Input LED Indicators
Power	
Input range	Unregulated +10 ~ +30 V _{DC} , 1.5 W

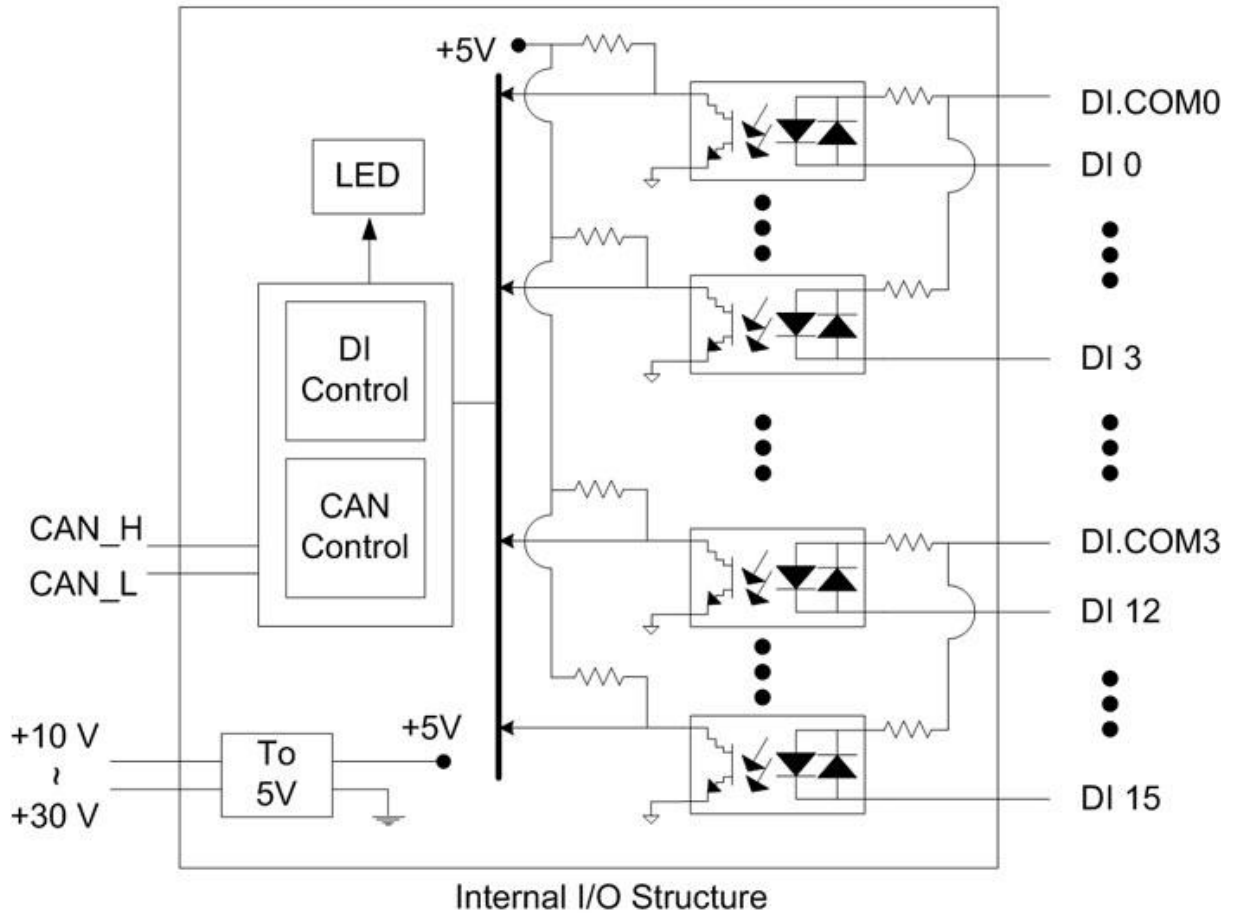
For more information about CAN-2053D, please visit the following website:

CAN-2053D

CAN-2053D Pin Assignments



CAN-2053D Internal I/O Structure



CAN-2053D Baud Rate Rotary Switch



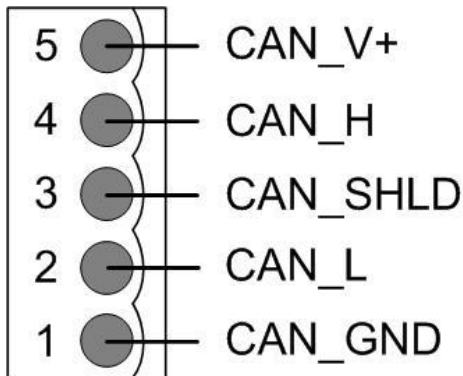
Baud rate rotary switch

Rotary Switch Value	Baud rate (kbps)
0x0	125
0x1	250
0x2	500
0xF	Firmware update

CAN-2053D Wiring Connection Type

Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
Relay Contact	Relay On	Relay On
	<p>Relay Close</p>	<p>Relay Open</p>
TTL/CMOS Logic	Voltage > 0 V	Voltage < 4 V
	<p>Logic Power</p> <p>Logic Level Low</p>	<p>Logic Power</p> <p>Logic Level Low</p>
NPN Output	Open Collector On	Open Collector Off
PNP Output	Open Collector On	Open Collector Off

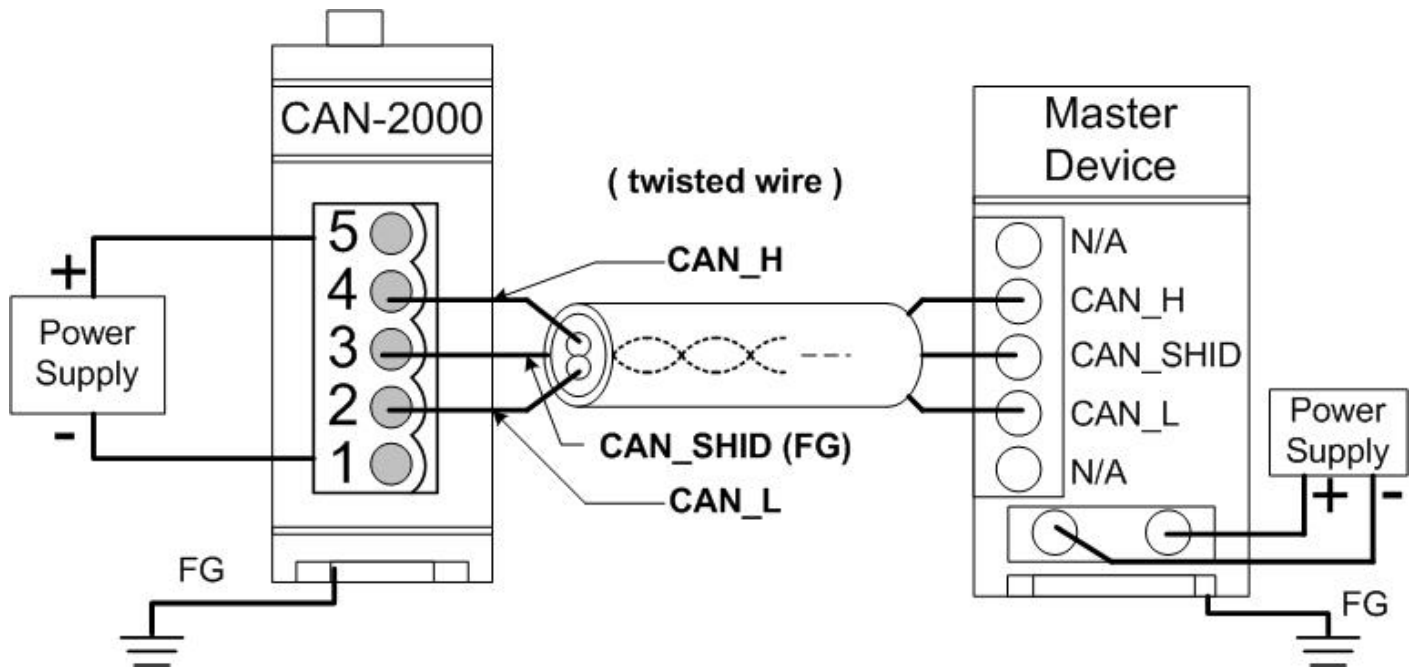
CAN-2053D CAN Bus Wire Connection



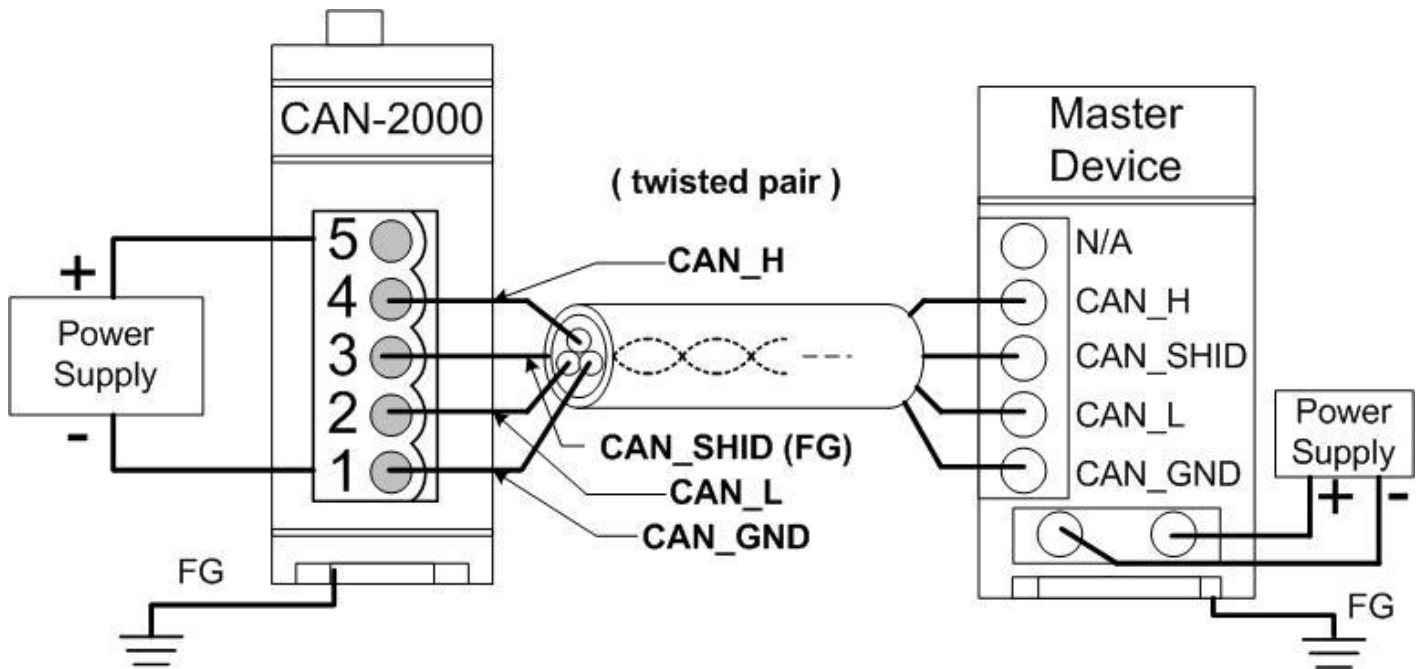
Pin	Signal	Description
5	CAN_V+	Power positive
4	CAN_H	Signal high of CAN Bus line
3	CAN_SHLD	Cable Shield (FG)
2	CAN_L	Signal low of CAN Bus line
1	CAN_GND	CAN ground

* CAN_SHID (FG) is Optional.

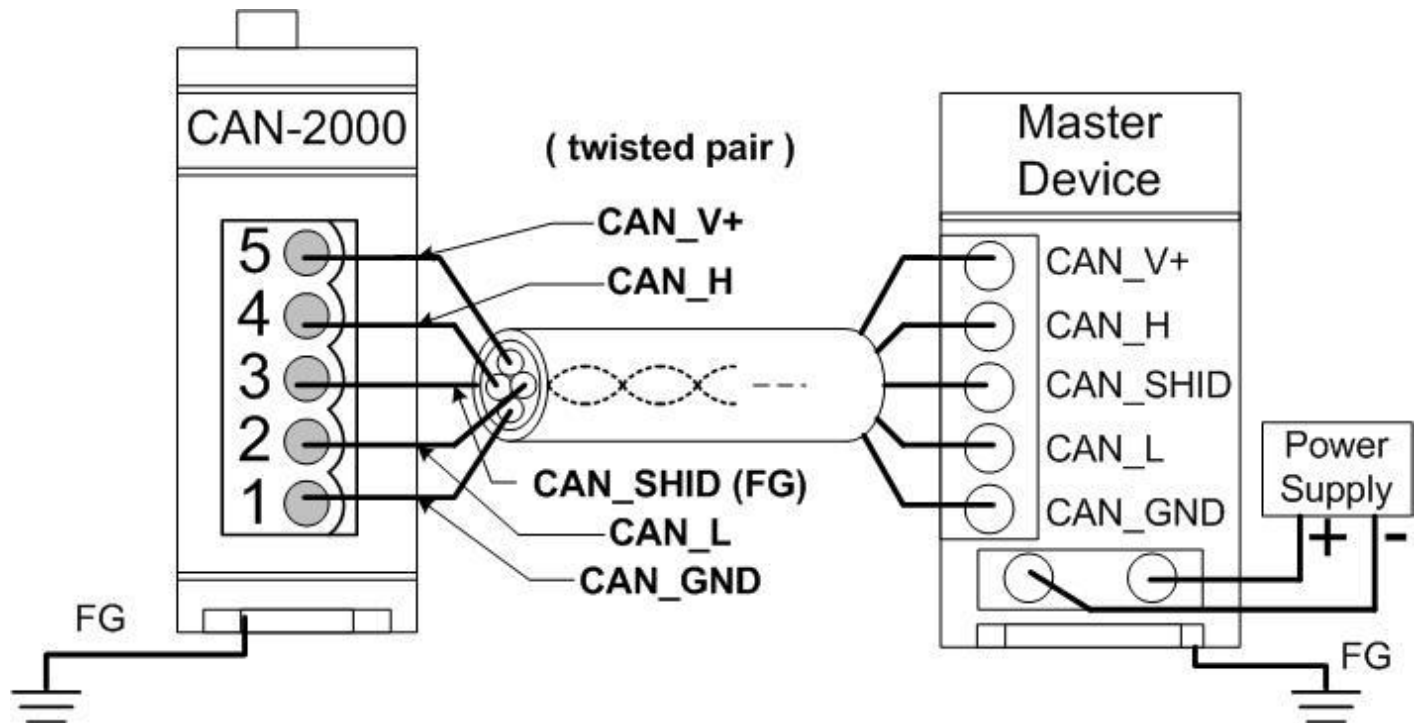
2-Wire Connection



3-Wire Connection

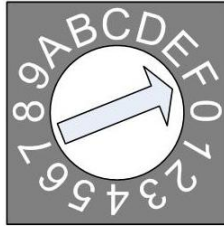


4-Wire Connection (The CAN-2000 is powered by the master device)



CAN-2053D Firmware Update

Step 1 – Set Module to “Bootloader” mode (set baud rate to 0xF). Then power on the module. After power on, the module’s led(PWR, NET, MOD) will be flashed at the same time. It means that the module have entered into “Bootloader” mode.



Baud Rate Rotary Switch

Step 2 – Run FW_Update_CAN Utility



(FW_Update_CAN Utility)

[1] CAN Device :

The below ICP DAS CAN products are supported by FW_Update_CAN utility for firmware update.

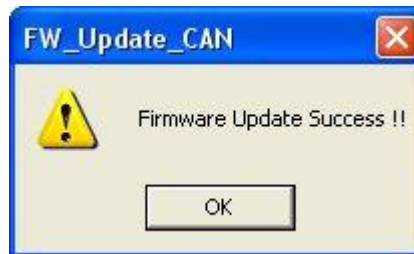
- (1) RS232 to CAN : I-7530
- (2) Ethernet to CAN : I-7540D
- (3) USB to CAN : I-7565, I-7565-H1, I-7565-H2
- (4) CAN Card : PISO-CM100(U),
PISO-/PCM-/PEX-CAN200 / CAN400

Before firmware update, users need to set the below parameters.

- (1) Select CAN hardware interface
- (2) set Dev_Port or Board_ID
- (3) set CAN_Port” number

[2] Download Firmware :

- (1) Click “**Browser...**” button to choose firmware file, can_2053d_vX.X.fw.
- (2) Click “**Start Firmware Update**” button to start firmware update and it will show the total percentage of firmware update in progress bar. After the firmware update finished, it will show the “Firmware Update Success !!” message.



CAN-2053D firmware Download:

ftp://ftp.icpdas.com.tw/pub/cd/fieldbus_cd/devicenet/slave/can-2000d/can-2053d/firmware/

FW_Update_CAN Utility Download:

ftp://ftp.icpdas.com.tw/pub/cd/fieldbus_cd/devicenet/slave/can-2000d/tools/fw_update_can_tool/