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# PISO-A64/C64/P64

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## Digital I/O Card

### Linux Software Manual

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## 1. Linux Software Installation

The PISO-A64/C64/P64 can be used in linux kernel 2.4.X and 2.6.X. For Linux O.S, the recommended installation and uninstall steps are given in Sec 1.1 ~ 1.2

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### 1.1 Linux Driver Installing Procedure

Step 1: Copy the linux driver "ixpio-0.20.15.tar.gz" (or the later driver version) in the directory "NAPDOS\Linux" of the companion CD or download the latest driver from our website to the linux host.

Step 2: You must use the '**root**' identity to compile and install PIO/PISO linux driver.

Step 3: Decompress the tarball "ixpio.tar.gz".

Step 4: Type '**cd**' to the directory containing the package's source code and type '**./configure**' to configure the package for your linux system.

Step 5: Type '**make**' to compile the package.

Step 6: You can type '**./ixpio.inst**' to install the PIO/PISO driver module and build the device file "ixpioX" in the device directory "/dev" automatically.

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### 1.2 Linux Driver Uninstalling Procedure

Step 1: Type '**cd**' to the directory containing the package's source code.

Step 2: Type '**./ixpio.remove**' to remove the PIO/PISO driver module.

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## 2. Static Library Function Description

The static library is the collection of function calls of the PIO-DIO cards for linux kernel 2.4.x and 2.6.x system. The application structure is presented as following figure. The user application program developed by C(C++) language can call library “libpio.a” in user mode. And then static library will call the module ixpio to access the hardware system.

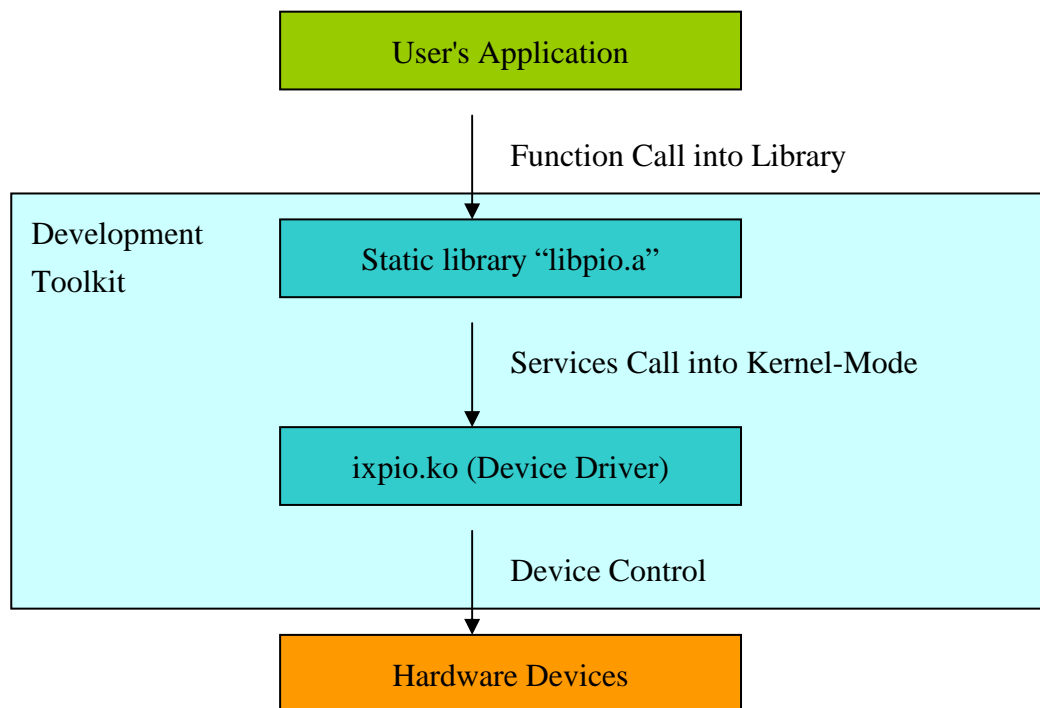


Figure 2.1

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## 2.1 Table of ErrorCode and ErrorString

Table 2.1

Error Code	Error ID	Error String
0	PIODA_NOERROR	OK ( No error !)
1	PIODA_MODULE_NAME_GET_ERROR	Module name can't get from file /proc/ixpio/ixpio
5	PIODA_DIGITAL_OUTPUT_ERROR	Digital output error
6	PIODA_DIGITAL_INPUT_ERROR	Digital input error

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## 2.2 Function Descriptions

Table 2.2

Function Definition
char * PIODA_GetDriverVersion(void);
char * PIODA_GetLibraryVersion(void);
int PIODA_Open(char *dev_file);
WORD PIODA_Close(WORD fd);
WORD PIODA_DriverInit(WORD);
WORD PIODA_Digital_Output(WORD, WORD, byte);
WORD PIODA_Digital_Input(WORD, WORD, WORD *);

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## 2.3 Digital I/O FUNCTIONS

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### 2.3.1 PIODA\_GetDriverVersion

- **Description:**  
To get the version number of PIO/PISO linux driver.
- **Syntax:**  
char \* PIODIO\_GetDriverVersion(Void)
- **Parameter:**  
None
- **Return:**  
The version of PIO/PISO linux driver.

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### 2.3.2 PIODA\_GetLibraryVersion

- **Description:**  
To get the version number of PIO/PISO linux static library.
- **Syntax:**  
`char * PIODIO_GetLibraryVersion(void)`
- **Parameter:**  
None
- **Return:**  
The version of PIO/PISO linux static library.

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### 2.3.3 PIODA\_Open

- **Description:**  
To open device file.
- **Syntax:**  
`int PIODIO_Open(char *dev_file)`
- **Parameter:**  
`dev_file` : The path of device file
- **Return:**  
The file descriptor of device file. If the file descriptor < 0, it means that open device file failure.

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### 2.3.4 PIODA\_Close

- **Description :**  
To close device file.
- **Syntax :**  
`Word PIODIO_Close(WORD fd)`
- **Parameter :**  
`fd` : The file descriptor of device file that get from function PIODIO\_Open
- **Return:**  
"PIODA\_NOERROR"  
(Please refer to "Section 2.1 Error Code")

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### 2.3.5 PIODA\_DriverInit

- **Description :**  
To allocates the computer resource for the device. This function must be

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called once before applying other PIODA functions.

- **Syntax :**  
WORD PIODA\_DriverInit(WORD fd)
- **Parameter :**  
fd : The file descriptor of device file that get from function PIODIO\_Open
- **Return:**  
"PIODA\_MODULE\_NAME\_GET\_ERROR"  
"PIODA\_NOERROR"  
(Please refer to "Section 2.1 Error Code")

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### 2.3.6 PIODA\_Digital\_Output

- **Description :**  
This subroutine for PISO-A64/C64 sends the 8 bits data to the specified I/O port.
- **Syntax :**  
WORD PIODA\_Digital\_Output(WORD fd, WORD port, byte data);
- **Parameter :**  
fd : The file descriptor of device file that get from function PIODIO\_Open.  
port : The value of DO port . Please refer to "Table 2.3" DO port ID.

Table 2.3

PISO-A64 Port ID	PISO-C64 Port ID	DO Port
PISOA64_DOA	PISOC64_DOA	DO 0 ~ DO 7
PISOA64 DOB	PISOC64 DOB	DO 8 ~ DO 15
PISOA64_DOC	PISOC64_DOC	DO 16 ~ DO 23
PISOA64_DOD	PISOC64_DOD	DO 24 ~ DO 31
PISOA64_DOE	PISOC64_DOE	DO 32 ~ DO 39
PISOA64 DOF	PISOC64 DOF	DO 40 ~ DO 47
PISOA64 DOG	PISOC64 DOG	DO 48 ~ DO 55
PISOA64 DOH	PISOC64 DOH	DO 56 ~ DO 63

data : 8 bits data.

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- **Return:**  
"PIODA\_DIGITAL\_OUTPUT\_ERROR"  
"PIODA\_NOERROR"  
(Please refer to "Section 2.1 Error Code")
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### 2.3.7 PIODA\_Digital\_Input

- **Description :**  
This subroutine for PISO-P64 reads the 8 bits data from the specified I/O port.
- **Syntax :**  
WORD PIODA\_Digital\_Input(WORD fd, WORD port, WORD \*di\_data);
- **Parameter :**  
fd : The file descriptor of device file that get from function PIODIO\_Open.  
port : The value of DI port. Please refer to "Table 2.4" DI port ID.

Table 2.4

PISO-P64 Port ID	DI Port
PISOP64_DIA	DI 0 ~ DI 7
PISOP64_DIB	DI 8 ~ DI 15
PISOP64_DIC	DI 16 ~ DI 23
PISOP64_DID	DI 24 ~ DI 31
PISOP64_DIE	DI 32 ~ DI 39
PISOP64_DIF	DI 40 ~ DI 47
PISOP64_DIG	DI 48 ~ DI 55
PISOP64_DIH	DI 56 ~ DI 63

di\_data : A variable address used to storage the 8 bits input data.

- **Return:**  
"PIODA\_DIGITAL\_INPUT\_ERROR"  
"PIODA\_NOERROR"  
(Please refer to "Section 2.1 Error Code")



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### 3. PISO-A64/C64/P64 Linux Demo

All of demo programs will not work normally if PIO/PISO linux driver would not be installed correctly. During the installation process of PIO/PISO linux driver, the install-scripts “ixpio.inst” will setup the correct kernel driver. After driver(version 0.20.15 or the later driver version) compiled and installation, the related demo programs, development library and declaration header files for different development environments are presented as follows.

Table 3.1

Driver Name	Directory Path	File Name	Description
ixpio-0.20.15	include	piodio.h	PIO/PISO library header
	lib	libpio.a	PIO/PISO static library
	examples/pisop64	port.c	Digital input demo
		port_a.c	DI demo with library
	examples/pisoa64 examples/pisoc64	port.c	Digital output demo
		port_a.c	DO demo with library

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#### 3.1 pisoa64/pisoc64 Demo code “port.c”

This demo program is used to output digital from DO 8 ~ 15.

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#### 3.2 pisoa64/pisoc64 Demo code “port\_a.c”

This demo program coded by using the static library “libpio.a”. It is used to output digital from DO 8 ~ 15.

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### **3.3 pisop64 Demo code “port.c”**

This demo program is used to output digital from DI 8 ~ 15.

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### **3.4 pisop64 Demo code “port\_a.c”**

This demo program coded by using the static library “libpio.a”. It is used to output digital from DI 0 ~ 7.